

2302EN V2.0.0



iD-GRIDM and Micro800 Modbus RTU Connection Operating Manual



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1. Remote I/O Module System Configuration List

Part No.	Specification	Description	
GFMS-RM01S	Master Modbus RTU, 1 Port	Main Controller	
GFDI-RM01N	Digital Input 16 Channel	Digital Input	
GFDO-RM01N	Digital Output 16 Channel / 0.5A	Digital Output	
GFPS-0202	Power 24V / 48W	Power Supply	
GFPS-0303	Power 5V / 20W	Power Supply	
0170-0101	8 pin RJ45 female connector/RS-485 Interface	Interface Module	

1.1 Product Description

- I. The interface module is used externally to convert micro800's communication port (Modbus RTU) to a RJ45 connector
- II. The main controller is in charge of the management and dynamic configuration of I/O parameters and so on.
- III. The power module and interface module are standard for remote I/Os and users can choose the model or brand they prefer.



2. Micro800 Connection Setup

This section details how to use the Connection Components Workbench program to connect Micro800 and D-GRID

2.1 Micro800 Hardware Connection

I. The connector is on the top side of the Micro800 and uses RS485 connections



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(View into terminal block) Pin 1 RS485 Data + Pin 2 RS485 Data -Pin 3 RS485 Ground⁽¹⁾ Pin 4 RS232 Receive Pin 5 RS232 Transmit Pin 6 RS232 Ground⁽¹⁾

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II. Connect the COM (RS485 A/B) on top of the Micro800 to the interface module (1/2) to convert it to a RJ45 connector before connecting it to the main controller





2.2 Micro800 Connection Setup

I. Launch the Connected Components Workbench software and click on the "Micro820" menu in the Item Manager on the left side



II. Click on "Serial Port" under the "Controller" menu





III. Set up the communication format in "Protocol Format"

控制器 - 串行端口								
通用设置								
驱动程序(R):	Modbus RTU 🖌 🛞							
波特率(U):	38400 ~							
奇偶校验(P):	无 ~							
Modbus 角色(L):	主站 ~							
协议控制								
介质(M):	RS485 ¥							
数据位:	8							
停止位(S):	1 ~							
响应计时器(I):	200 ms							
广播暂停(O):	200 ms							
帧间(N): (延时/超时)	0 µs							
For "Driver", select "MODE	BUS_RTU COM"							
For "Baud Rate", select "38400"								
For "Parity", select "None"								
For "Modbus Role", select "Master"								
For "Medium", select "RS485"								
For "Stop Bit, select "1"								

 \times The communication format setting must be consistent with $\Box - \Box R D M$

% If the texts in the driver are gray, please switch to "Remote LCD", and uncheck "Assign Serial Port for Remote LCD"

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IV. Master Program Settings

In the master M820, MSG_MODBUS commands are used to read the register on the iD-GRID (slave). As illustrated below, different data types for the commands are created using the local variables of the program

名称	别名	数据类型		维度	项目值	初始值
* IT	- IT		- T	- IT	▼ IT	- IT
MSG_MODBUS_1		MSG_MODBUS	*			
🖃 Target_Add		MODBUSTARPARA	•			
Target_Add.Addr		UDINT				8193
Target_Add.Node		USINT				1
🖃 Local_cfg		MODBUSLOCPARA	+			
Local_cfg.Channel		UINT				2
Local_cfg.TriggerType		USINT				1
Local_cfg.Cmd		USINT				16
Local_cfg.ElementCnt		UINT				10
🛨 Local_Add	MODBUSLOCADDR	+				

Addr: The address of the D-GRID *m* register to be read or written

Node: Slave station number

Channel:

- 2: For the embedded serial ports
- 5: Slot 1
- 6: Slot 2
- 7: Slot 3
- 8: Slot 4
- 9: Slot 5

Trigger Type:

- 0: When MSG is triggered once (When "IN" goes from "False" to "True")
- 1: When "IN" is "True", the MSG is triggered continuously

Cmd:

03: Read and keep the register (s)

16: Write in multiple registers

ElementCnt: The amount of data to read or write

Notes:

* ID-GRID^W's first GFDI-RM01N has the register address at 4097 GRID^W's first GFDO-RM01N has the register address at 8193 DAUDIN CO., LTD.

V. Programming Example:

Create command block "MSG_MODBUS" and enter the variables just created into the block

